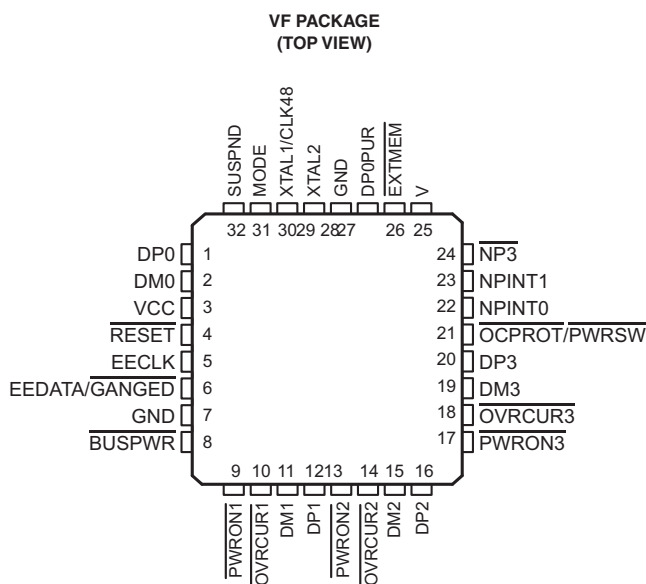


2/3-PORT HUB FOR THE UNIVERSAL SERIAL BUS WITH OPTIONAL SERIAL EEPROM INTERFACE

Check for Samples: [TUSB2036](#)

FEATURES

- Fully Compliant With the USB Specification as a Full-Speed Hub: TID #30220242
- Integrated USB Transceivers
- 3.3-V Low Power ASIC Logic
- One Upstream Port and 2–3 Programmable Downstream Ports
 - Total Number of Ports (2 or 3) Selected by Input Terminal
 - Total Number of Permanently Connected Ports Is Selected by 2 Input Terminals
- Two Power Source Modes
 - Self-Powered Mode
 - Bus-Powered Mode
- All Downstream Ports Support Full-Speed and Low-Speed Operations
- Power Switching and Overcurrent Reporting Is Provided Ganged or Per Port
- Supports Suspend and Resume Operations
- Suspend Status Terminal Available for External Logic Power Down
- Supports Custom Vendor ID and Product ID With External Serial EEPROM
- 3-State EEPROM Interface Allows EEPROM Sharing
- Push-Pull Outputs for $\overline{\text{PWRON}}$ Eliminate the Need for External Pullup Resistors
- Noise Filtering on $\overline{\text{OVRCUR}}$ Provides Immunity to Voltage Spikes
- Supports 6-MHz Operation Through a Crystal Input or a 48-MHz Input Clock
- Output Terminal Available to Disable External Pullup Resistor on DP0 for 3 ms After Reset or After Change on $\overline{\text{BUSPWR}}$ and Enable Easy Implementation of On-Board Bus/Self-Power Dynamic Switching Circuitry
- Available in 32-Terminal LQFP Package With a 0.8-mm Terminal Pitch (JEDEC – S-PQFP-G For Low-Profile Quad Flat Pack)



ORDERING INFORMATION⁽¹⁾

T _A	PACKAGE ⁽²⁾		ORDERABLE PART NUMBER	TOP-SIDE MARKING
0°C to 70°C	LQFP – VF	Reel of 250	TUSB2036VF	TUSB2036
			TUSB2036VFG4	
		Reel of 1000	TUSB2036VFR	
			TUSB2036VFRG4	

(1) Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.

(2) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

DESCRIPTION

The TUSB2036 hub is a 3.3-V CMOS device that provides up to three downstream ports in compliance with the USB 2.0 specification. Because this device is implemented with a digital state machine instead of a microcontroller, no firmware programming is required. Fully-compliant USB transceivers are integrated into the ASIC for all upstream and downstream ports. The downstream ports support both full-speed and low-speed devices by automatically setting the slew rate according to the speed of the device attached to the ports. The configuration of the BUSPWR terminal selects either the bus-powered or the self-powered mode. The introduction of the DP0 pullup resistor disable terminal, DP0PUR, makes it much easier to implement an on-board bus/self-power dynamic-switching circuitry. With the new function terminal, the end-equipment vendor can reduce the total board cost while adding additional product value.

The $\overline{\text{EXTMEM}}$ (terminal 26) enables or disables the optional EEPROM interface. When $\overline{\text{EXTMEM}}$ is high, the vendor and product IDs (VID and PID) use defaults, such that the message displayed during enumeration is General Purpose USB Hub. For this configuration, terminal 6 functions as the $\overline{\text{GANGED}}$ input terminal and the $\overline{\text{EECLK}}$ (terminal 5) is unused. If custom VID and PID descriptors are desired, the $\overline{\text{EXTMEM}}$ must be tied low ($\overline{\text{EXTMEM}} = 0$) and a SGS Thompson M93C46 EEPROM, or equivalent, stores the programmable VID, PID, and $\overline{\text{GANGED}}$ values. For this configuration, terminals 5 and 6 function as the EEPROM interface signals with terminal 5 as $\overline{\text{EECLK}}$ and terminal 6 as $\overline{\text{EEDATA}}$, respectively.

The TUSB2036 supports both bus-powered and self-powered modes. External power-management devices, such as the TPS2044, are required to control the 5-V power source switching (on/off) to the downstream ports and to detect an overcurrent condition from the downstream ports individually or ganged. Outputs from external power devices provide overcurrent inputs to the TUSB2036 $\overline{\text{OVRCUR}}$ terminals in case of an overcurrent condition, the corresponding $\overline{\text{PWRON}}$ terminals are disabled by the TUSB2036. In the ganged mode, all $\overline{\text{PWRON}}$ signals transition simultaneously, and any $\overline{\text{OVRCUR}}$ input can be used. In the nonganged mode, the $\overline{\text{PWROR}}$ outputs and $\overline{\text{OVRCUR}}$ inputs operate on a per-port basis.

The TUSB2036 provides the flexibility of using either a 6-MHz or a 48-MHz clock. The logic level of the MODE terminal controls the selection of the clock source. When MODE is low, the output of the internal APLL circuitry is selected to drive the internal core of the chip. When MODE is high, the XTAL1 input is selected as the input clock source and the APLL circuitry is powered down and bypassed. The internal oscillator cell is also powered down while MODE is high. For 6-MHz operation, TUSB2036 requires a 6-MHz clock signal on XTAL1 terminal (with XTAL2 for a crystal) from which its internal APLL circuitry generates a 48-MHz internal clock to sample the data from the upstream port. For 48-MHz operation, the clock cannot be generated with a crystal, using the XTAL2 output, since the internal oscillator cell only supports the fundamental frequency. If low-power suspend and resume are desired, a passive crystal or resonator must be used, although the hub supports the flexibility of using any device that generates a 6-MHz clock. Because most oscillators cannot be stopped while power is on, their use prohibits low-power suspend, which depends on disabling the clock. When the oscillator is used, by connecting its output to the XTAL1 terminal and leaving the XTAL2 terminal open, its TTL output level can not exceed 3.6 V. If a 6-MHz oscillator is used, it must be stopped at logic low whenever SUSPND is high. For crystal or resonator implementations, the XTAL1 terminal is the input and the XTAL2 terminal is used as the feedback path. A sample crystal tuning circuit is shown in [Figure 7](#).

The hub silicon can accurately reflect the system port configuration by the $\overline{\text{NP3}}$ and NPINT1-0 terminals. When $\overline{\text{NP3}}$ is low, the hub is configured as a 3-port hub; when it is high, the hub is configured as a 2-port hub. The NPINT1-0 terminals tell the hub silicon how many ports have permanently attached devices, according to [Table 1](#).

TERMINAL FUNCTIONS

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
$\overline{\text{BUSBWR}}$	8	I	Power source indicator. $\overline{\text{BUSBWR}}$ is an active-low input that indicates whether the downstream ports source their power from the USB cable or a local power supply. For the bus-power mode, this terminal must be pulled low, and for the self-powered mode, this terminal must be pulled to 3.3 V. Input must not change dynamically during operation.
DM0	2	I/O	Root port USB differential data minus. DM0 paired with DP0 constitutes the upstream USB port.
DM1–DM3	11, 15, 19	I/O	USB differential data minus. DM1–DM3 paired with DP1–DP3 support up to four downstream USB ports.
DP0	1	I/O	Root port USB differential data plus. DP0 paired with DM0 constitutes the upstream USB port.
DP0PUR	27	O	Pullup resistor connection. When a system reset happens ($\overline{\text{RESET}}$ being driven to low, but not USB reset) or any logic level change on $\overline{\text{BUSBWR}}$ terminal, DP0PUR output is inactive (floating) until the internal counter reaches a 15-ms time period. After the counter expires, DP0PUR is driven to the VCC (3.3 V) level thereafter until the next system reset event occurs or there is a $\overline{\text{BUSBWR}}$ logic level change.
DP1–DP3	12, 16, 20	I/O	USB differential data plus. DP1–DP3 paired with DM1–DM3 support up to four downstream USB ports.
EECLK	5	O	EEPROM serial clock. When $\overline{\text{EXTMEM}}$ is high, the EEPROM interface is disabled. The EECLK terminal is disabled and must be left floating (unconnected). When $\overline{\text{EXTMEM}}$ is low, EECLK acts as a 3-state serial clock output to the EEPROM with a 100- μA internal pulldown.
$\overline{\text{EEDATA}}/\overline{\text{GANGED}}$	6	I/O	EEPROM serial data/power-management mode indicator. When $\overline{\text{EXTMEM}}$ is high, $\overline{\text{EEDATA}}/\overline{\text{GANGED}}$ selects between ganged or per-port power overcurrent detection for the downstream ports. When $\overline{\text{EXTMEM}}$ is low, $\overline{\text{EEDATA}}/\overline{\text{GANGED}}$ acts as a serial data I/O for the EEPROM and is internally pulled down with a 100- μA pulldown. This standard TTL input must not change dynamically during operation.
$\overline{\text{EXTMEM}}$	26	I	When $\overline{\text{EXTMEM}}$ is high, the serial EEPROM interface of the device is disabled. When $\overline{\text{EXTMEM}}$ is low, terminals 5 and 6 are configured as the clock and data terminals of the serial EEPROM interface, respectively.
GND	7, 28		GND terminals must be tied to ground for proper operation.
$\overline{\text{OCPROT}}/\overline{\text{PWRSW}}$	21	I	Overcurrent Protection for bus-powered hub (active low). /Power Switching for self-powered hub (active low). The terminal has a different meaning for the bus or self-powered hub. If the terminal is logic high the internal pulldown is disabled. ^{(1) (2)}
$\overline{\text{OVRCUR1}} - \overline{\text{OVRCUR3}}$	10, 14, 18	O	Overcurrent input. $\overline{\text{OVRCUR1}} - \overline{\text{OVRCUR3}}$ are active low. For per-port overcurrent detection, one overcurrent input is available for each of the three downstream ports. In the ganged mode, any $\overline{\text{OVRCUR}}$ input may be used and all $\overline{\text{OVRCUR}}$ terminals must be tied together. $\overline{\text{OVRCUR}}$ terminals are active low inputs with noise filtering logic. Each $\overline{\text{OVRCURn}}$ input is sampled every 2 ms and any input which is valid for two consecutive samples will be passed to the internal logic. $\overline{\text{OVRCUR3}}$ has an internal pull-up that can be enabled for the 2-port operation.
$\overline{\text{PWRON1}} - \overline{\text{PWRON3}}$	9, 13, 17	O	Power-on/off control signals. $\overline{\text{PWRON1}} - \overline{\text{PWRON3}}$ are active low, push-pull outputs that enables the external power switch device. Push-pull outputs eliminate the pullup resistors which open-drain outputs require. However, the external power switches that connect to these terminals must be able to operate with 3.3-V inputs because these outputs cannot drive 5-V signals.
$\overline{\text{RESET}}$	4	I	$\overline{\text{RESET}}$ is an active low TTL input with hysteresis and must be asserted at power up. When $\overline{\text{RESET}}$ is asserted, all logic is initialized. Generally, a reset with a pulse width between 100 μs and 1 ms is recommended after 3.3-V V_{CC} reaches its 90%. Clock signal has to be active during the last 60 μs of the reset window.
SUSPND	32	O	Suspend status. SUSPND is an active high output available for external logic power-down operations. During the suspend mode, SUSPND is high. SUSPND is low for normal operation.
MODE	31		Mode select. When MODE is low, the APLL output clock is selected as the clock source to drive the internal core of the device and 6-MHz crystal or oscillator can be used. When MODE is high, the clock on XTAL1/CLK48 is selected as the clock source and 48-MHz oscillator or other on-board clock source can be used.
$\overline{\text{NP3}}$	24		Number of ports is 3. Active low input. A logic 0 configures the system to use 3 ports. A logic 1 configures the system to use 2 ports.
NPINT1–0	22, 23		Number of ports internal to hub system, which are permanently attached (see Table 1).

- (1) If the hub is implemented to be bus-powered (via $\overline{\text{BUSBWR}}$ tying to GND):
 - (a) TUSB2036 reports to the host that the hub end-product downstream ports are power-switched (this is required by the USB 2.0 specification). Hub end-product vendor has to ensure the actual end-product implementation meets this specification requirement.
 - (b) Terminal 21 acts as overcurrent protection ($\overline{\text{OCPROT}}$) implementation indication terminal for the bus-powered hub. The overcurrent protection implementation is reported through the wHubCharacteristics. D4 bit in the hub descriptor.
 - (c) When $\overline{\text{OCPROT}}$ is low, the TUSB2036 reports to the host that the hub end-product provides overcurrent protection and the wHubCharacteristics. D4 bit is set to 0.
 - (d) When $\overline{\text{OCPROT}}$ is high, the TUSB2036 reports to the host that the hub end-product does not provide overcurrent protection and the wHubCharacteristics. D4 bit is set to 1.
- (2) If the hub is implemented to be self-powered (via $\overline{\text{BUSBWR}}$ tying to 3.3-V V_{CC}):
 - (a) TUSB2036 reports to the host that the hub end-product provides overcurrent protection to the downstream ports (this is required by the USB 2.0 specification). Hub end-product vendor has to ensure the actual end-product implementation meets this specification requirement.
 - (b) Terminal 21 acts as power switching ($\overline{\text{PWRSW}}$) implementation indication terminal for the self-powered hub. The power-switching implementation is reported through the bPwrOn2PwrGood field in the hub descriptor.
 - (c) When $\overline{\text{PWRSW}}$ is low, the TUSB2036 reports to the host that the hub end-product has port power switching at the downstream ports and the bPwrOn2PwrGood is set to 50 units (100 ms).
 - (d) When $\overline{\text{PWRSW}}$ is high, the TUSB2036 reports to the host that the hub end-product does not have port power switching at the downstream ports and the bPwrOn2PwrGood is set to 0 units (0 ms).

TERMINAL FUNCTIONS (continued)

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
V _{CC}	3, 25		3.3-V supply voltage
XTAL1/CLK48	30	I	Crystal 1/48-MHz clock input. When MODE is low, XTAL1/CLK48 is a 6-MHz crystal input with 50% duty cycle. An internal APLL generates the 48-MHz and 12-MHz clocks used internally by the ASIC logic. When MODE is high, XTAL1/CLK48 acts as the input of the 48-MHz clock and the internal APLL logic is bypassed.
XTAL2	29	O	Crystal 2. XTAL2 is a 6-MHz crystal output. This terminal must be left open when using an oscillator.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
V _{CC}	Supply voltage range ⁽²⁾	-0.5	3.6	V
V _I	Input voltage range	-0.5	V _{CC} + 0.5	V
V _O	Output voltage range	-0.5	V _{CC} + 0.5	V
I _{IK}	Input clamp current	V _I < 0 V or V _I < V _{CC}		±20 mA
I _{OK}	Output clamp current	V _O < 0 V or V _O < V _{CC}		±20 mA
T _{stg}	Storage temperature range	-65	150	°C
T _A	Operating free-air temperature range	0	70	°C

(1) Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage levels are with respect to GND.

RECOMMENDED OPERATING CONDITIONS

PARAMETER		MIN	NOM	MAX	UNIT
V _{CC}	Supply voltage	3	3.3	3.6	V
V _I	Input voltage, TTL/LVCMOS ⁽¹⁾	0		V _{CC}	V
V _O	Output voltage, TTL/LVCMOS ⁽²⁾	0		V _{CC}	V
V _{IH(REC)}	High-level input voltage, signal-ended receiver	2		V _{CC}	V
V _{IL(REC)}	Low-level input voltage, signal-ended receiver			0.8	V
V _{IH(TTL)}	High-level input voltage, TTL/LVCMOS ⁽¹⁾	2		V _{CC}	V
V _{IL(TTL)}	Low-level input voltage, TTL/LVCMOS ⁽¹⁾	0		0.8	V
T _A	Operating free-air temperature	0		70	°C
R _(DRV)	External series, differential driver resistor	22 (-5%)		22 (+5%)	Ω
f _(OPRH)	Operating (dc differential driver) high speed mode			12	Mb/s
f _(OPRL)	Operating (dc differential driver) low speed mode			1.5	Mb/s
V _{ICR}	Common mode, input range, differential receiver	0.8		2.5	V
t _t	Input transition times, TTL/LVCMOS ⁽¹⁾	0		25	ns
T _J	Junction temperature range ⁽³⁾	0		115	°C

(1) Applies for input and bidirectional buffers.

(2) Applies for output and bidirectional buffers.

(3) These junction temperatures reflect simulated conditions. Absolute maximum junction temperature is 150°C. The customer is responsible for verifying junction temperature.

ELECTRICAL CHARACTERISTICS

over recommended ranges of operating free-air temperature and supply voltage (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT	
V _{OH}	High-level output voltage	TTL/LVCMOS	I _{OH} = -4 mA	V _{CC} - 0.5	V	
		USB data lines	R _(DRV) = 15 kΩ to GND	2.8		
			I _{OH} = -12 mA (without R _(DRV))	V _{CC} - 0.5		
V _{OL}	Low-level output voltage	TTL/LVCMOS	I _{OL} = 4 mA	0.5	V	
		USB data lines	R _(DRV) = 1.5 kΩ to 3.6 V	0.3		
			I _{OL} = 12 mA (without R _(DRV))	0.5		
V _{IT+}	Positive input threshold	TTL/LVCMOS		1.8	V	
		Single-ended	0.8 V ≤ V _{ICR} ≤ 2.5 V	1.8		
V _{IT-}	Negative-input threshold	TTL/LVCMOS		0.8	V	
		Single-ended	0.8 V ≤ V _{ICR} ≤ 2.5 V	1		
V _{hys}	Input hysteresis ⁽¹⁾ (V _{T+} - V _{T-})	TTL/LVCMOS		0.3	0.7	mV
		Single-ended	0.8 V ≤ V _{ICR} ≤ 2.5 V	300	500	
I _{OZ}	High-impedance output current	TTL/LVCMOS	V = V _{CC} or GND ⁽²⁾	±10	μA	
		USB data lines	0 V ≤ V _O ≤ V _{CC}	±10		
I _{IL}	Low-level input current	TTL/LVCMOS	V _I = GND	-1	μA	
I _{IH}	High-level input current	TTL/LVCMOS	V _I = V _{CC}	1	μA	
Z _{0(DRV)}	Driver output impedance	USB data lines	Static V _{OH} or V _{OL}	7.1	19.9	Ω
V _{ID}	Differential input voltage	USB data lines	0.8 V ≤ V _{ICR} ≤ 2.5 V	0.2		V
I _{CC}	Input supply current		Normal operation	40	mA	
			Suspend mode	1	μA	

(1) Applies for input buffers with hysteresis.

(2) Applies for open drain buffers.

DIFFERENTIAL DRIVER SWITCHING CHARACTERISTICS Full Speed Mode

over recommended ranges of operating free-air temperature and supply voltage, C_L = 50 pF (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
t _r	Transition rise time for DP or DM	See Figure 1 and Figure 2	4	20	ns
t _f	Transition fall time for DP or DM	See Figure 1 and Figure 2	4	20	ns
t _(RFM)	Rise/fall time matching ⁽¹⁾	(t _r /t _f) × 100	90	110	%
V _{O(CRS)}	Signal crossover output voltage ⁽¹⁾		1.3	2.0	V

(1) Characterized only. Limits are approved by design and are not production tested.

DIFFERENTIAL DRIVER SWITCHING CHARACTERISTICS Low Speed Mode

over recommended ranges of operating free-air temperature and supply voltage, C_L = 50 pF (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
t _r	Transition rise time for DP or DM ⁽¹⁾	C _L = 200 pF to 600 pF, See Figure 1 and Figure 2	75	300	ns
t _f	Transition fall time for DP or DM ⁽¹⁾	C _L = 200 pF to 600 pF, See Figure 1 and Figure 2	75	300	ns
t _(RFM)	Rise/fall time matching ⁽¹⁾	(t _r /t _f) × 100	80	120	%
V _{O(CRS)}	Signal crossover output voltage ⁽¹⁾	C _L = 200 pF to 600 pF	1.3	2.0	V

(1) Characterized only. Limits are approved by design and are not production tested.

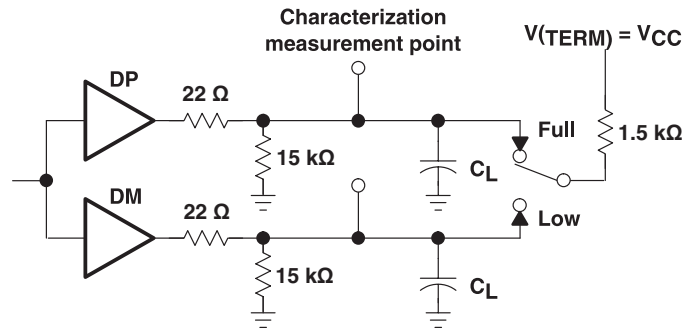
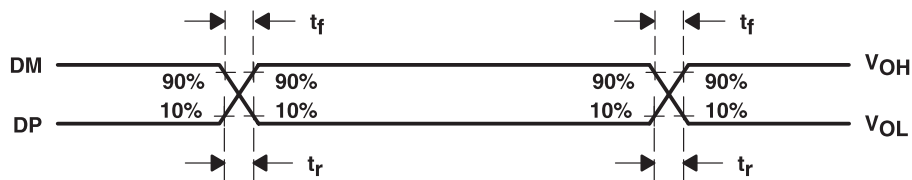


Figure 1. Differential Driver Switching Load



NOTE: The t_r/t_f ratio is measured as $t_r(DP)/t_f(DM)$ and $t_r(DM)/t_f(DP)$ at each crossover point.

Figure 2. Differential Driver Timing Waveforms

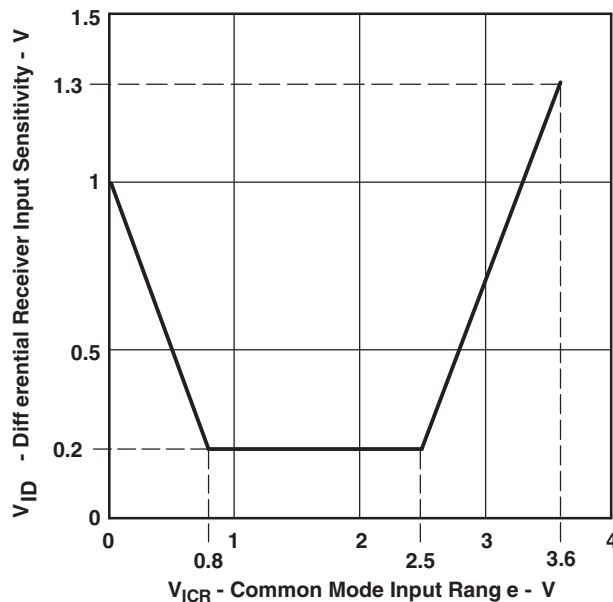


Figure 3. Differential Receiver Input Sensitivity vs Common Mode Input Range

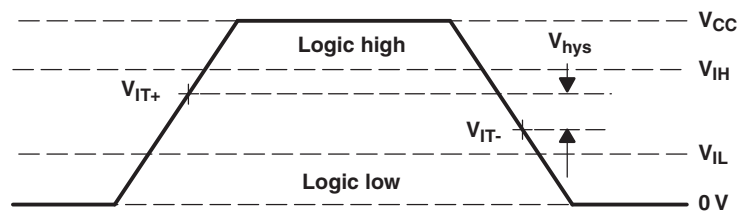


Figure 4. Single-Ended Receiver Input Signal Parameter Definitions

APPLICATION INFORMATION

A major advantage of USB is the ability to connect 127 functions configured in up to 6 logical layers (tiers) to a single personal computer (see [Figure 5](#)).

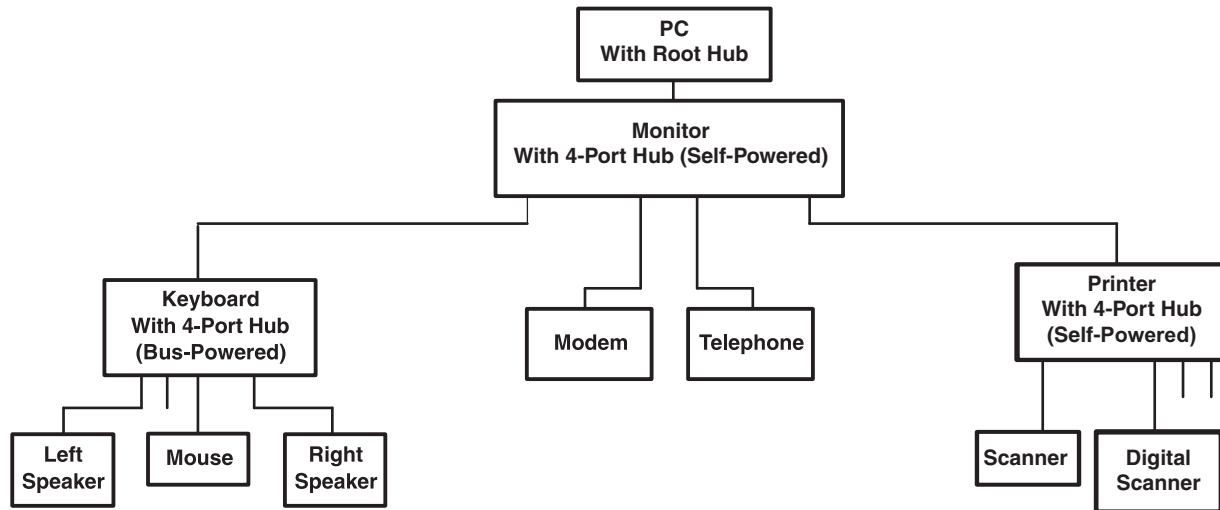


Figure 5. USB-Tiered Configuration Example

Another advantage of USB is that all peripherals are connected using a standardized four-wire cable that provides both communication and power distribution. The power configurations are bus-powered and self-powered modes. The maximum current that may be drawn from the USB 5-V line during power up is 100 mA. For the bus-powered mode, a hub can draw a maximum of 500 mA from the 5-V line of the USB cable. A bus-powered hub must always be connected downstream to a self-powered hub unless it is the only hub connected to the PC and there are no high-powered functions connected downstream. In the self-powered mode, the hub is connected to an external power supply and can supply up to 500 mA to each downstream port. High-powered functions may draw a maximum of 500 mA from each downstream port and may only be connected downstream to self-powered hubs. Per the USB specification, in the bus-powered mode, each downstream port can provide a maximum of 100 mA of current, and in the self-powered mode, each downstream port can provide a maximum of 500 mA of current.

Both bus-powered and self-powered hubs require overcurrent protection for all downstream ports. The two types of protection are individual-port management (individual-port basis) or ganged-port management (multiple-port basis). Individual-port management requires power-management devices for each individual downstream port, but adds robustness to the USB system because, in the event of an overcurrent condition, the USB host only powers down the port that has the condition. The ganged configuration uses fewer power management devices and thus has lower system costs, but in the event of an overcurrent condition on any of the downstream ports, all the ganged ports are disabled by the USB host.

Using a combination of the $\overline{\text{BUSPWR}}$ and $\overline{\text{EEDATA/GANGED}}$ inputs, the TUSB2036 supports four modes of power management: bus-powered hub with either individual-port power management or ganged-port power management, and the self-powered hub with either individual-port power management or ganged-port power management. Texas Instruments supplies the complete hub solution because we offer this TUSB2036 along with the power-management devices needed to implement a fully USB compliant system.

USB Design Notes

The following sections provide block diagram examples of how to implement the TUSB2036 device. Note, even though no resistors are shown, pullup, pulldown, and series resistors must be used to properly implement this device.

Figure 6 is a block diagram example of how to connect the external EEPROM if a custom product ID and vendor ID are desired.

Figure 7 is an example of how to generate the 6-MHz clock signal.

Figure 8 shows the EEPROM read operation timing diagram.

Figure 9, Figure 10, Figure 11, and Figure 12 illustrate how to connect the TUSB2036 device for different power source and port power-management combinations.

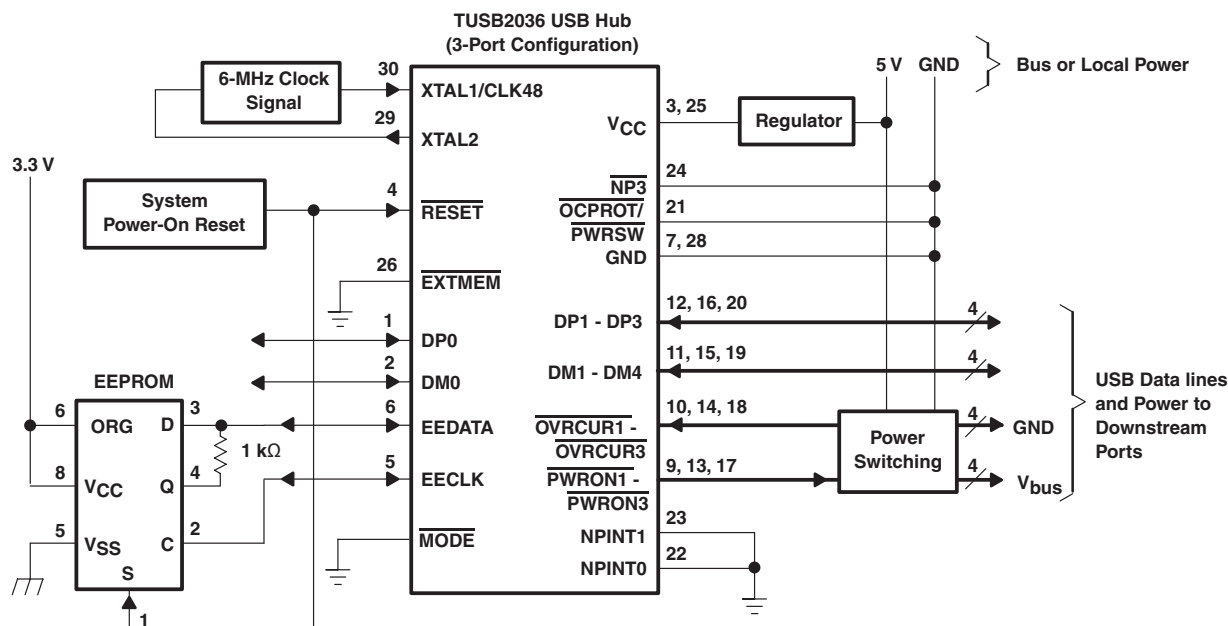
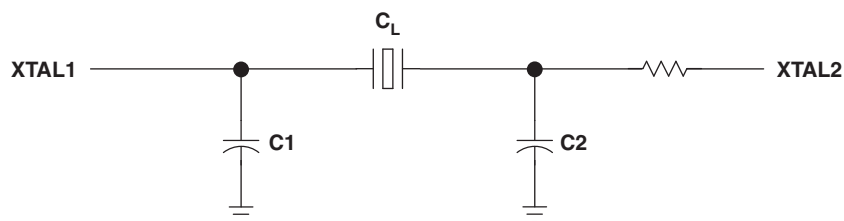


Figure 6. Typical Application of the TUSB2036 USB Hub



NOTE: This figure assumes a 6-MHz fundamental crystal that is parallel loaded. The component values of C1, C2, and R_d are determined using a crystal from Fox Electronics – part number HC49U-6.00MHz 30\50\0±70\20, which means ± 30 ppm at 25°C and ± 50 ppm from 0°C to 70°C. The characteristics for the crystal include a load capacitance (C_L) of 20 pF, maximum shunt capacitance (C_0) of 7 pF, and the maximum ESR of 50 Ω . In order to insure enough negative resistance, use $C1 = C2 = 27$ pF. The resistor R_d is used to trim the gain, and $R_d = 1.5$ k Ω is recommended.

Figure 7. Crystal Tuning Circuit

Programming the EEPROM

An SGS Thompson M93C46 EEPROM, or equivalent, stores the programmable VID and PID. When the EEPROM interface is enabled ($\overline{\text{EXTMEM}} = 0$), the EECLK and EEDATA are internally pulled down (100 μA) inside the TUSB2036. The internal pulldowns are disabled when the EEPROM interface is disabled ($\overline{\text{EXTMEM}} = 1$).

The EEPROM is programmed with the three 16-bit locations as shown in Table 2. Connecting terminal 6 of the EEPROM high (ORG = 1) organizes the EEPROM memory into 64×16-bit words.

Table 2. EEPROM Memory Map

ADDRESS	D15	D14	D13	D12–D8	D7–D0
00000	0	$\overline{\text{GANGED}}$	00000	00000	00000000
00001	VID High-byte				VID Low-byte
00010	PID High-byte				PID Low-byte
XXXXXXXX					

The D and Q signals of the EEPROM must be tied together using a 1-k Ω resistor with the common I/O operations forming a single-wire bus. After system power-on reset, the TUSB2036 performs a one-time access read operation from the EEPROM if the $\overline{\text{EXTMEM}}$ terminal is pulled low and the chip select(s) of the EEPROM is connected to the system power-on reset. Initially, the EEDATA terminal is driven by the TUSB2036 to send a start bit (1) which is followed by the read instruction (10) and the starting-word address (00000). Once the read instruction is received, the instruction and address are decoded by the EEPROM, which then sends the data to the output shift register. At this point, the hub stops driving the EEDATA terminal and the EEPROM starts driving. A dummy (0) bit is then output and the first three 16-bit words in the EEPROM are output with the most significant bit (MSB) first.

The output data changes are triggered by the rising edge of the clock provided by the TUSB2036 on the EECLK terminal. The SGS-Thompson M936C46 EEPROM is recommended because it advances to the next memory location by automatically incrementing the address internally. Any EEPROM used must have the automatic internal address advance function. After reading the three words of data from the EEPROM, the TUSB2036 puts the EEPROM interface into a high-impedance condition (pulled down internally) to allow other logic to share the EEPROM. The EEPROM read operation is summarized in Figure 8. For more details on EEPROM operation, refer to *SGS-Thompson Microelectronics M93C46 Serial Microwire Bus EEPROM* data sheet.

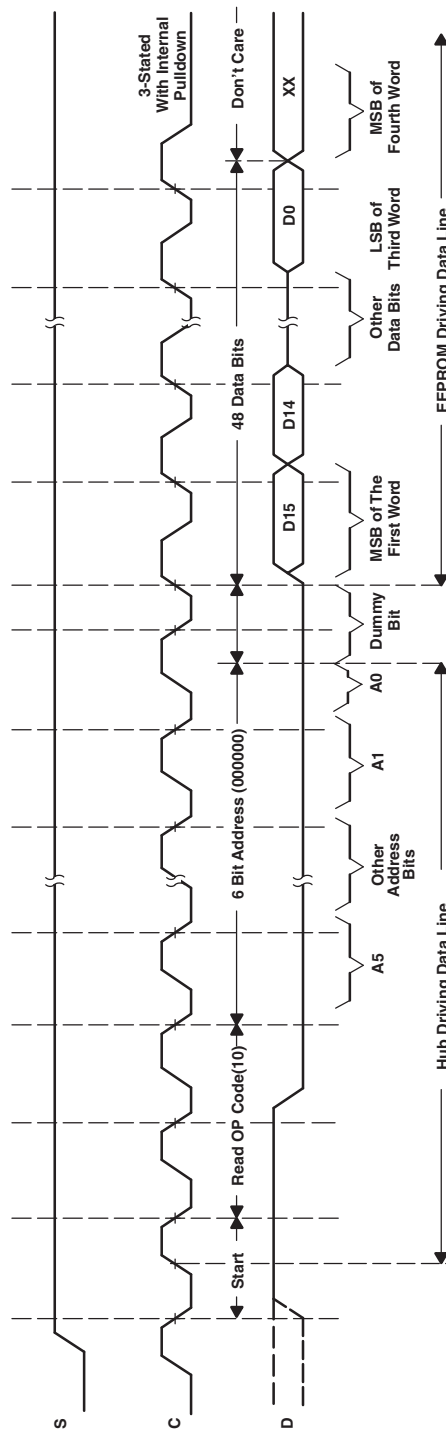
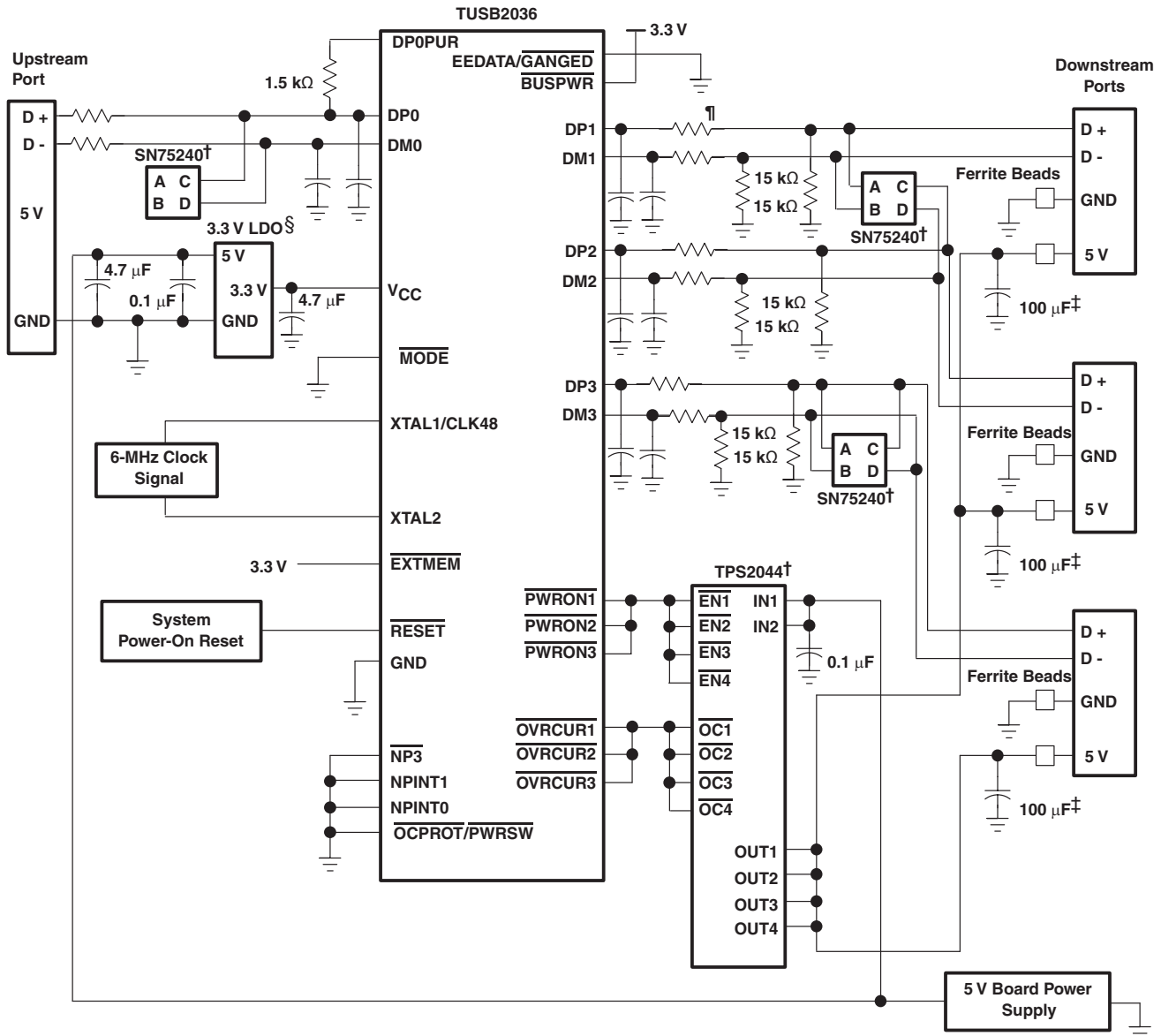


Figure 8. EEPROM Read Operation Timing Diagram

Self-Powered Hub, Ganged-Port Power Management

The TUSB2036 can also be implemented for ganged-port power management in a self-powered configuration. The implementation is very similar to the bus-powered example with the exception that a self-powered port supplies 500 mA of current to each downstream port. The overcurrent protection can be provided by a TPS2044 quad device or a TPS2024 single power switch.



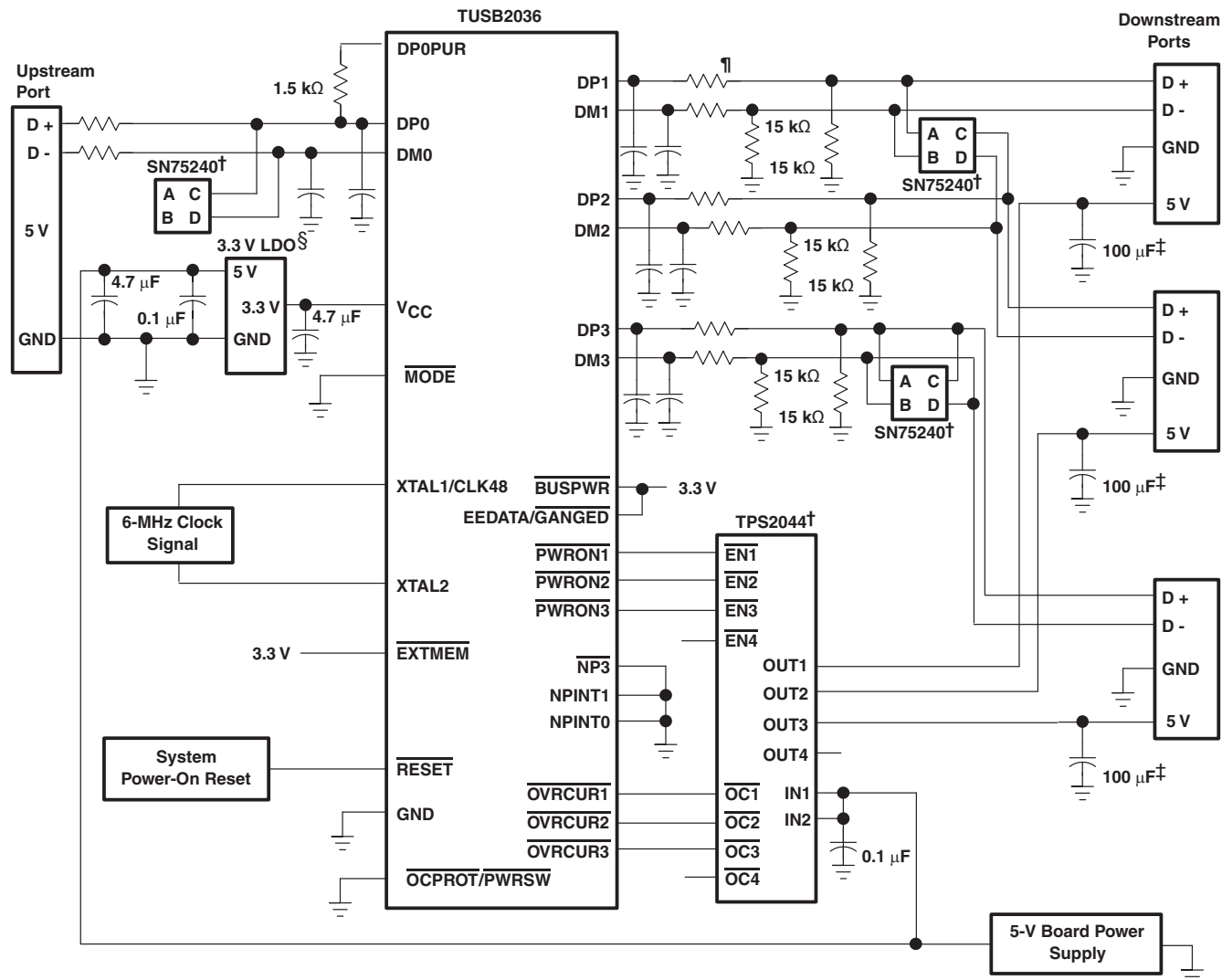
- NOTES: † TPS2044, TPS2042, and SN75240 are Texas Instruments devices. The TPS2024 can be substituted for the TPS2044.
 ‡ 120 µF per hub is the minimum required per the USB specification. However, TI recommends a 100-µF, low ESR, tantalum capacitor per port for immunity to voltage droop.
 § LDO is a 5-V-to-3.3-V voltage regulator. TPS76333 from Texas Instruments can be used.
 ¶ All USB DP, DM signal pairs require series resistors of approximately 27Ω to ensure proper termination. An optional filter capacitor of about 22 pF is recommended for EMI suppression. This capacitor, if used, must be placed between the hub terminal and the series resistor, as per section 7.1.6 of the USB specification.

Figure 11. TUSB2036 Self-Powered Hub, Ganged-Port Power-Management Application

Self-Powered Hub, Individual-Port Power Management

In a self-powered configuration, the TUSB2036 can be implemented for individual-port power management when

used with the TPS2044 because it is capable of supplying 500 mA of current to each downstream port and can provide current limiting on a per-port basis. When the hub detects a fault on a downstream port, power is removed from only the port with the fault and the remaining ports continue to operate normally. Self-powered hubs are required to implement overcurrent protection and report overcurrent conditions. The SN75240 transient suppressors reduce inrush current and voltage spikes on the data lines.



- NOTES: † TPS2042 and SN75240 are Texas Instruments devices. Two TPS2042 devices can be substituted for the TPS2044.
‡ 120 μF per hub is the minimum required per the USB specification. However, TI recommends a 100-μF, low ESR, tantalum capacitor per port for immunity to voltage droop.
§ LDO is a 5-V-to-3.3-V voltage regulator. TPS76333 from Texas Instruments can be used.
¶ All USB DP, DM signal pairs require series resistors of approximately 27Ω to ensure proper termination. An optional filter capacitor of about 22 pF is recommended for EMI suppression. This capacitor, if used, must be placed between the hub terminal and the series resistor, as per section 7.1.6 of the USB specification.

Figure 12. TUSB2036 Self-Powered Hub, Individual-Port Power-Management Application

PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	Eco Plan ⁽²⁾	Lead/ Ball Finish	MSL Peak Temp ⁽³⁾	Samples (Requires Login)
TUSB2036VF	ACTIVE	LQFP	VF	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
TUSB2036VFG4	ACTIVE	LQFP	VF	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
TUSB2036VFR	ACTIVE	LQFP	VF	32	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
TUSB2036VFRG4	ACTIVE	LQFP	VF	32	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

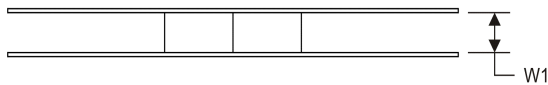
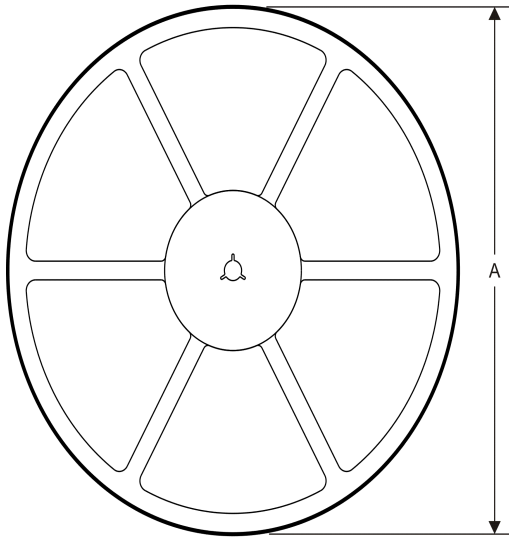
⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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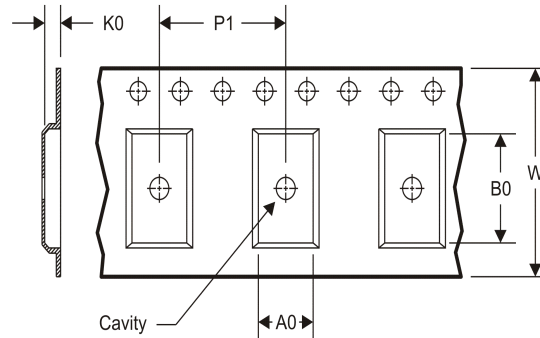
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TAPE AND REEL INFORMATION

REEL DIMENSIONS



TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

TAPE AND REEL INFORMATION

*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TUSB2036VFR	LQFP	VF	32	1000	330.0	16.4	9.6	9.6	1.9	12.0	16.0	Q2

TAPE AND REEL BOX DIMENSIONS

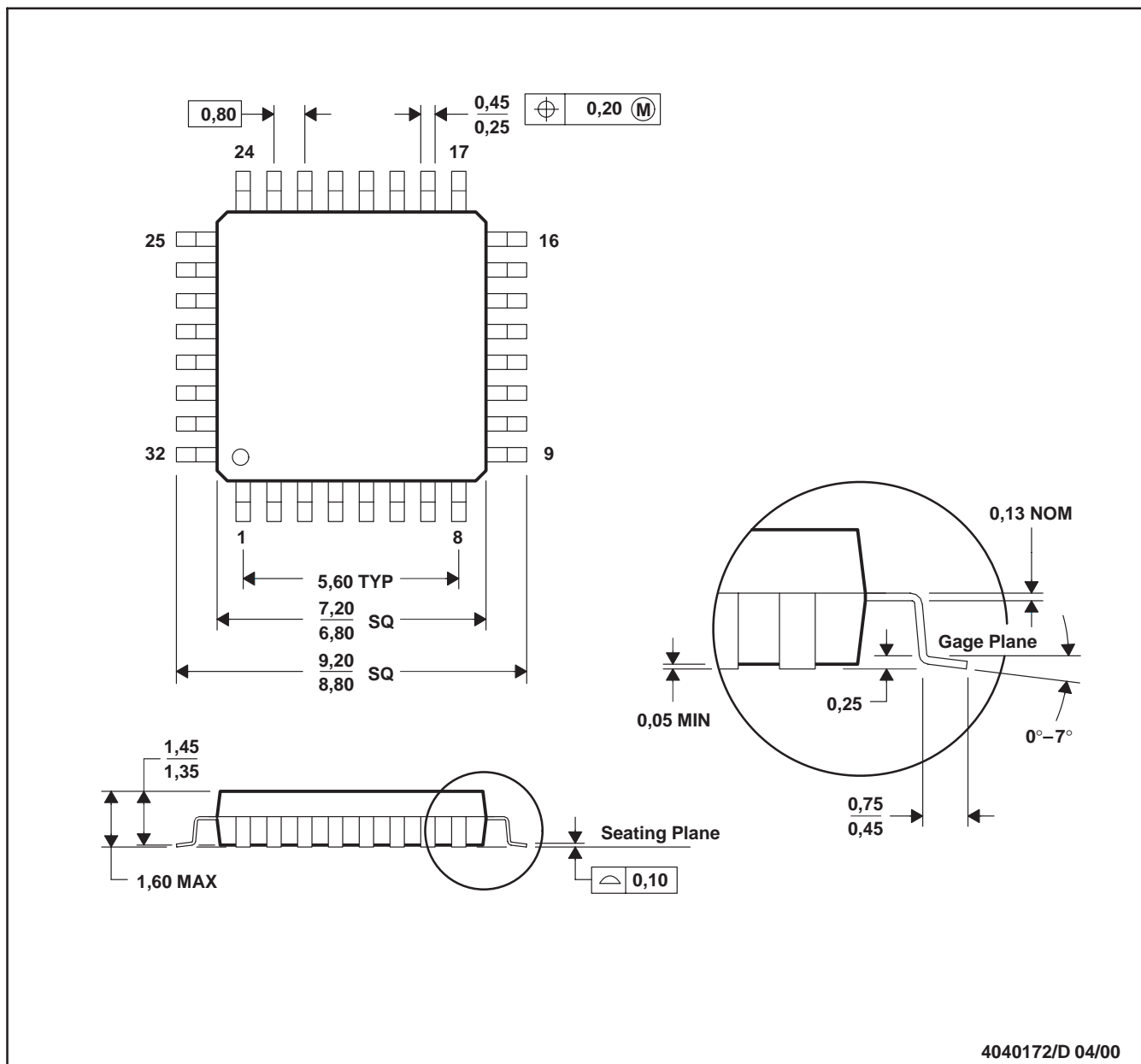


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TUSB2036VFR	LQFP	VF	32	1000	336.6	336.6	31.8

VF (S-PQFP-G32)

PLASTIC QUAD FLATPACK



4040172/D 04/00

- NOTES: A. All linear dimensions are in millimeters.
 B. This drawing is subject to change without notice.

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